

0.1 Chapter 3 – Electrostatics

0.1.1 Coulomb's Law

$$\vec{E}(r) = \frac{1}{4\pi\epsilon_0} \int \frac{\hat{r}}{r^2} \rho(r') d\tau' \quad (1)$$

0.1.2 Dipole Moment Definition

$$\vec{p} = \int \vec{r}' \rho(\vec{r}') d\tau' \quad (2)$$

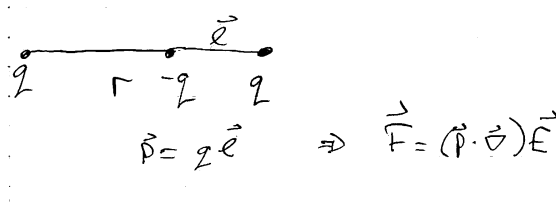


Figure 1: Geometry of a dipole

Force on a dipole due to a monopole:

$$\vec{p} = ql \quad (3)$$

$$\vec{F} = (\vec{p} \cdot \vec{\nabla}) \vec{E} \quad (4)$$

$$(5)$$

where \vec{l} is the direction vector from the negative to the positive pole.

Electric Dipoles (see Fig 1):

$$\vec{E} = \frac{P}{4\pi\epsilon_0 r^3} (2 \cos \theta \hat{r} + \sin \theta \hat{\theta})$$

Torque on a dipole:

$$\vec{\tau} = \vec{p} \times \vec{E}$$

Potential associated with a dipole \vec{p}

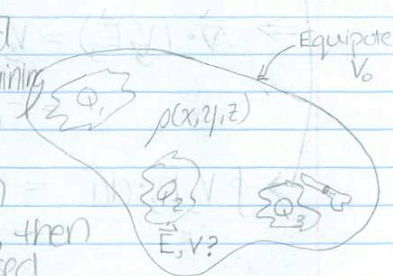
$$V_{\text{dip}} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$$

0.1.3 Uniqueness Theorem

See figures 2 and 3.

phys 340 October 12, 2007

Second Uniqueness Theorem
 In a volume surrounded by an equipotential, containing specified charge density $\rho(x,y,z)$ and containing individual conductors with total charges Q_1, Q_2, Q_3, \dots , then the E -field within the closed boundary is uniquely determined.



Proof
 Assume two solns: \vec{E}_1, \vec{E}_2

between conductors: $\vec{\nabla} \cdot \vec{E}_1 = \frac{\rho}{\epsilon_0}$ $\vec{\nabla} \cdot \vec{E}_2 = \frac{\rho}{\epsilon_0}$

boundaries around conductors:

$$\oint_{\text{conductor } i} \vec{E}_1 \cdot d\vec{a} = \frac{Q_i}{\epsilon_0} \quad \oint_{\text{conductor } i} \vec{E}_2 \cdot d\vec{a} = \frac{Q_i}{\epsilon_0}$$

outer boundary: $\oint_{\text{outer boundary}} \vec{E}_1 \cdot d\vec{a} = \frac{Q_{\text{tot}}}{\epsilon_0}$ $\oint_{\text{outer boundary}} \vec{E}_2 \cdot d\vec{a} = \frac{Q_{\text{tot}}}{\epsilon_0}$

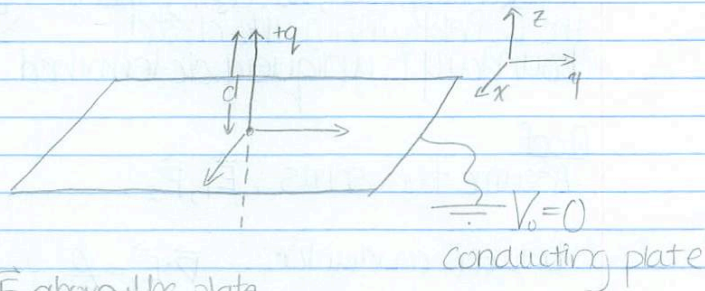
between conductors: $\vec{E}_3 = \vec{E}_2 - \vec{E}_1$

① $\vec{\nabla} \cdot \vec{E}_3 = \vec{\nabla} \cdot (\vec{E}_2 - \vec{E}_1) = \vec{\nabla} \cdot \vec{E}_2 - \vec{\nabla} \cdot \vec{E}_1 = 0$

② $\oint_{\text{outer boundary and boundaries of the conductors}} \vec{E}_3 \cdot d\vec{a} = 0$

Figure 2: Uniqueness Theorem part 1

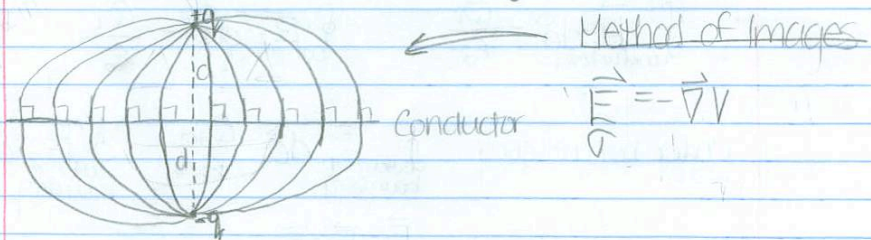
$$\begin{aligned}
 & \int \vec{\nabla} \cdot (V_3 \vec{E}) dV \\
 \Rightarrow & \vec{\nabla} \cdot (V_3 \vec{E}) = V_3 (\vec{\nabla} \cdot \vec{E}) + \vec{E} \cdot (\vec{\nabla} V_3) \\
 & \quad \quad \quad = -|\vec{E}_3|^2 \quad \quad \quad \vec{\nabla} V_3 = -\vec{E}_3 \\
 \Rightarrow & \oint V_3 \vec{E} \cdot d\vec{a} = V_3 \oint \vec{E} \cdot d\vec{a} = 0 = \int (-|\vec{E}_3|^2) dV
 \end{aligned}$$



What is \vec{E} above the plate?

What is V above the plate?

What is the distribution of charge on the surface of the plate?



$$V(x, y, z) = V_q(x, y, z) + V_{-q}(x, y, z)$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{q}{\sqrt{x^2 + y^2 + (z-d)^2}} + \frac{-q}{\sqrt{x^2 + y^2 + (z+d)^2}} \right) + V_0$$

Figure 3: Uniqueness Theorem part 2

0.1.4 Separation of Variables

In a region of no charge density $\rho = 0$ then the laplacian of the potential is zero $\vec{\nabla}^2 V = 0$.

Assume a solution

$$V(x, y, z) = A(x)B(y)C(z)$$

then

$$A''(x)B(y)C(z) + A(x)B''(y)C(z) + A(x)B(y)C''(z) = 0 \quad (6)$$

$$\frac{A''(x)}{A(x)} + \frac{B''(y)}{B(y)} + \frac{C''(z)}{C(z)} = 0 \quad (7)$$

$$C_1 + C_2 + C_3 = 0 \quad (8)$$

See Figures 4, 5 and 6.

0.2 ODE Solutions

$$\frac{d^2 Y}{dy^2} = k^2 Y \rightarrow R^2 = k^2 \quad (9)$$

$$y'' = R^2, y' = R, y = 1 \quad (10)$$

$$Y(y) = C_1 e^{ky} + C_2 e^{-ky} \quad (11)$$

If you have $R = ik$ (i.e. $R^2 = -k^2$) then you use a general solution :

$$Y(y) = C_1 \sin(ky) + C_2 \cos(ky)$$

0.3 Chapter 5 – Magnetism

Force on a moving charge due to a magnetic field:

$$\vec{F}_{\text{mag}} = q(\vec{v} \times \vec{B}) \quad (12)$$

$$\vec{F} = Q(\vec{E} + (\vec{v} \times \vec{B})) \quad (13)$$

Magnetic forces depending on the current geometry:

$$\vec{F} = I \int (d\vec{l} \times \vec{B}) \quad \vec{I} = \lambda \vec{v} \quad (14)$$

$$= \int (\vec{K} \times \vec{B}) da \quad \vec{K} = \sigma \vec{v} \quad (15)$$

$$= \int (\vec{J} \times \vec{B}) dV \quad \vec{J} = \rho \vec{v} \quad (16)$$

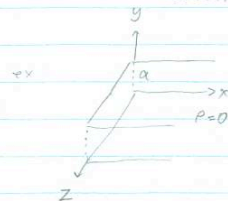
15 Oct - 340 - 18

Laplace's Eq'n $\nabla^2 V = \rho = 0$, how to find V ?If the geometry of the Boundary Potential's can be described by separate variables, then so the sol'n $V(x, y, z) = X(x)Y(y)Z(z)$

$$\nabla^2 V = YZ \frac{d^2 X}{dx^2} + XZ \frac{d^2 Y}{dy^2} + XY \frac{d^2 Z}{dz^2}$$

$$\frac{1}{V} \nabla^2 V = \frac{1}{X} \frac{d^2 X}{dx^2} + \frac{1}{Y} \frac{d^2 Y}{dy^2} + \frac{1}{Z} \frac{d^2 Z}{dz^2} = 0$$

constant,

 C_2 C_3 which $C_1 + C_2 + C_3 = 0$ 

2-semi-infinite plane

- ① $x-z$ plane $V=0$ at $y=0$ and $y=a$
- ② $V=V_0$ when $x=0$
- ③ $V \rightarrow 0$ as $x \rightarrow \infty$

1. $\rightarrow Z(z) = 1$

2. $\rightarrow \nabla^2 V = C_1 + C_2 = 0$

$$\frac{d^2 X}{dx^2} = C_1 X(x) \rightarrow C_1 = K^2 \quad C_2 = -C_1 = -K^2$$

$$X(x) = Ae^{Kx} + Be^{-Kx} \quad Y(y) = C \sin(Ky) + D \cos(Ky)$$

Boundary ① $x \rightarrow \infty \quad V \rightarrow 0$ so $A = 0$

② $V=0$ at $y=0$ and a so $D=0$ now make $B \times C = A$

now $Ae^{-Kx} \sin(Ka) = 0 \quad K = \frac{n\pi}{a} \quad n \in \mathbb{Z}^+ \quad \sum C_n \sin \frac{n\pi}{a}$

since $V(0,0,\infty, z) = V_0 \quad \sum C_n \sin \frac{n\pi}{a} = V_0$

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Figure 4: Separation of Variables part 1

Oct 9/9 340 - 120

$$Y(y) = \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi}{a}y\right) = V_0$$

$$\int_0^a \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi}{a}y\right) \sin\left(\frac{n'\pi}{a}y\right) dy = \int_0^a V_0 \sin\left(\frac{n'\pi}{a}y\right) dy$$

bring C_n out of integral

$$\int_0^a \sin\left(\frac{n\pi}{a}y\right) \sin\left(\frac{n'\pi}{a}y\right) dy = \begin{cases} 0 & \text{if } n \neq n' \\ \frac{a}{2} & \text{if } n = n' \end{cases} \rightarrow \frac{a}{2} \delta_{n,n'}$$

$$C_{n'} = \frac{2}{a} \int_0^a V_0 \sin\left(\frac{n'\pi}{a}y\right) dy = \frac{2V_0}{a} \left[-\cos\left(\frac{n'\pi}{a}y\right) \frac{a}{n'\pi} \right]_0^a$$

$$= \frac{2V_0}{n'\pi} [1 - \cos(n'\pi)] = \frac{4V_0}{n'\pi} \text{ for } n' = 1, 3, 5 \text{ and } 0 \text{ for } n' = 0, 2, 4$$

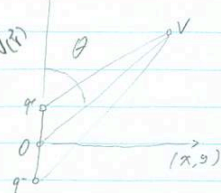
$$V(x, y, z) = \sum_{n=1,3,5}^{\infty} \frac{4V_0}{n\pi} e^{-\frac{n\pi x}{a}} \sin\left(\frac{n\pi y}{a}\right)$$

The Dipole



$$V(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{q}{r_+} + \frac{q}{r_-} \right) = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{r_+} - \frac{1}{r_-} \right)$$

must define a coordinate



$$\text{then we have } V(r) = \frac{q}{4\pi\epsilon_0} \frac{d}{r^2} \cos\theta$$

a dipole has a direction $|\vec{P}| = qd$

so

$$V(r) = \frac{1}{4\pi\epsilon_0} \frac{\vec{P} \cdot \hat{r}}{r^2}$$

$$\vec{E}(r) = -\vec{\nabla} V(r) = -\left[\frac{\partial}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} \hat{\phi} \right] \frac{1}{4\pi\epsilon_0} \frac{P \cos\theta}{r^2}$$

$$= \frac{P}{4\pi\epsilon_0 r^3} (2 \cos\theta \hat{r} + \sin\theta \hat{\theta})$$

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Figure 5: Separation of Variables part 2

ODE Solutions

$$A''(x) + \lambda A(x) = 0 \quad \lambda \in \mathbb{R}$$

Case 1: $\lambda < 0$

$$A(x) = a \cosh(\sqrt{\lambda} x) + b \sinh(\sqrt{\lambda} x) \quad (a, b) \in \mathbb{R}$$

$$S = -\lambda$$

Case 2: $\lambda = 0$

$$A(x) = ax + b$$

$$S = 0$$

Case 3: $\lambda > 0$

$$A(x) = a \cos(\sqrt{\lambda} x) + b \sin(\sqrt{\lambda} x)$$

Figure 6: ODEs useful for the Uniqueness Theorem

Continuity equations :

$$\vec{\nabla} \cdot \vec{J} = -\frac{d\rho}{dt}$$

for magnetostatics $\vec{\nabla} \cdot \vec{J} = 0$.

0.3.1 Biot-Savart Law

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} \times \hat{r}}{|\vec{r}|^2} dl' \quad (17)$$

$$= \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}') \times \hat{r}}{|\vec{r}|^2} da' \quad (18)$$

$$= \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times \hat{r}}{|\vec{r}|^2} dV' \quad (19)$$

0.4 Magnetic Maxwell's Equations

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad (20)$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad (21)$$

$$\int (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \oint \vec{B} \cdot d\vec{l} \quad (22)$$

$$= \mu_0 \int \vec{J} \cdot d\vec{a} \quad (23)$$

$$\text{so } \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} \text{ (Ampere's Law)} \quad (24)$$

$$(25)$$

0.4.1 Electric Maxwell's Equations

$$\int \vec{E} \cdot d\vec{a} = \frac{Q_{\text{enc}}}{\epsilon} \text{ (Gauss' Law)} \quad (26)$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad (27)$$

$$\vec{\nabla} \times \vec{E} = 0 \quad (28)$$

Magnetostatic Vector Potential:

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad (29)$$

$$\vec{\nabla} \cdot \vec{A} = 0 \quad (30)$$

$$\vec{\nabla}^2 \vec{A} = -\mu_0 \vec{J} \quad (31)$$

Definition of the Vector Potential:

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{|\vec{r}|} dV' \quad (32)$$

$$= \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}')}{|\vec{r}|} da' \quad (33)$$

$$= \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{|\vec{r}|} \quad (34)$$

Dipoles:

$$m = I \int da = I(\text{area}) \quad (35)$$

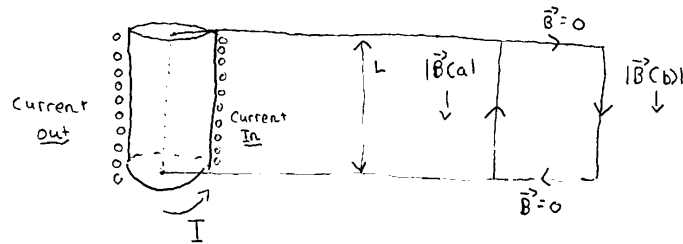
$$\vec{B}_{\text{dip}}(\vec{r}) = \frac{\mu_0 m}{4\pi r^3} (2 \cos \theta \hat{r} + \sin \theta \hat{\theta}) \quad (36)$$

0.4.2 Cyclotron Motion

$$QvB = \frac{mv^2}{\text{Radius}} \quad (37)$$

Infinite Solenoid

χ loops/unit length



$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{enc}$$

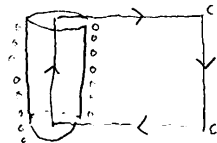
$$(-B(a)L) + B(b)L = \mu_0 I_{enc} = 0 \quad (\text{no current outside cylinder})$$

$$B(b)L - B(a)L = 0$$

$$B(a) = B(b)$$

Far away, the solenoid looks like a simple line of current. $B(\infty) = 0$,
 $\therefore \vec{B} = 0$ outside.

Inside:



$$\vec{B}_{center} \cdot L = 0 \cdot c + 0 \cdot L + 0 \cdot c = \mu_0 I_{enc} = \mu_0 \chi L I$$

\therefore

$$\vec{B}_{center} = \mu_0 \chi I \Rightarrow \text{everywhere inside}$$

Figure 7: Infinite Solenoid Problem

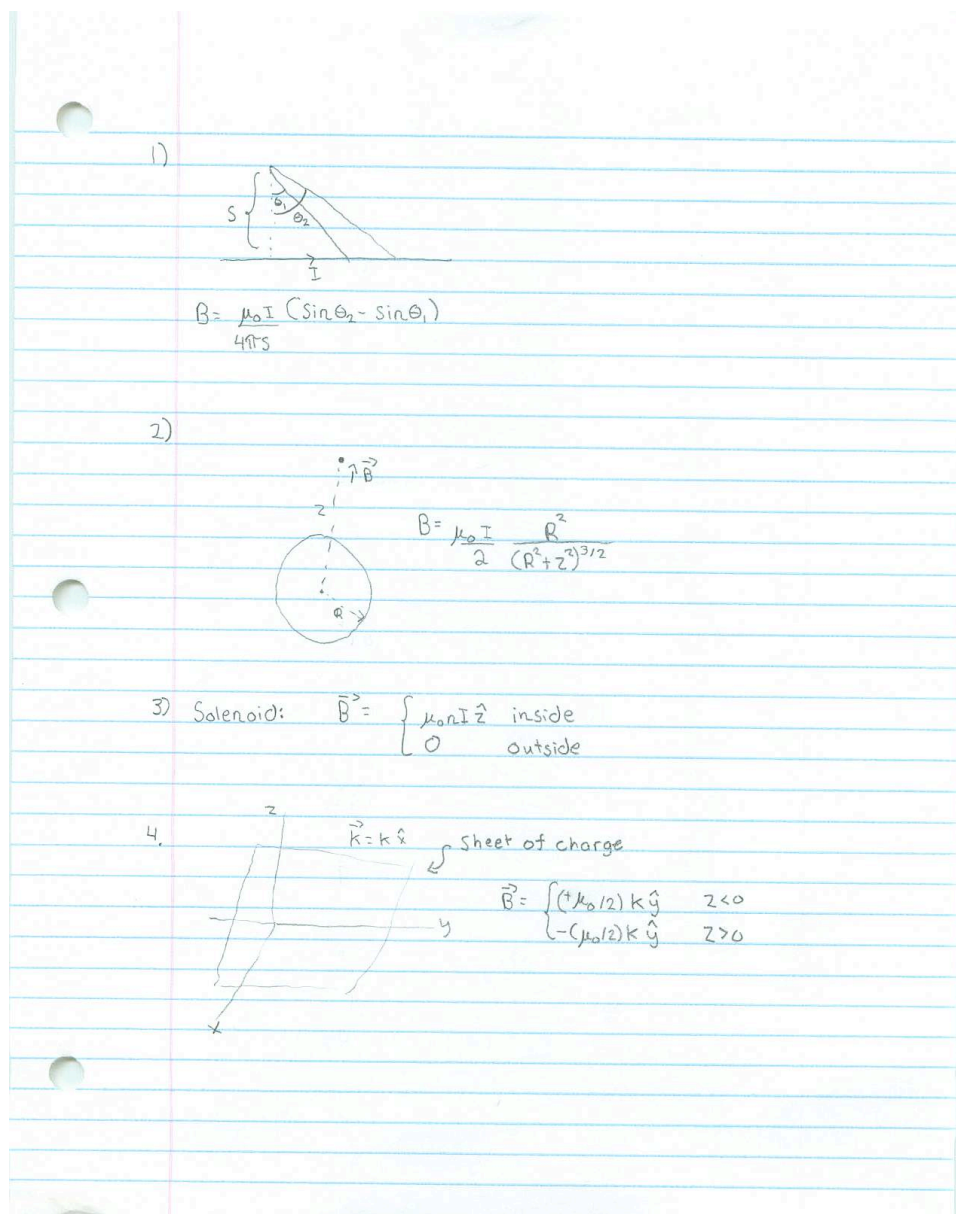


Figure 8: Current Geometries and B-field Solutions.