

# Physics 257, Section One, Lab Five: Rotational Dynamics

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## 1 Data and Results

Apparatus no. 8.

The data in Table 1 are the specifications.

Table 2 are the measurements for Part 1.

Table 3 are the measurements for Part 1b.

Table 4 are the calculations for Part 1b.

We want to force the line to go through the origin, thus no calculations for  $b$  are done in Table 5.

The data in Table 1 are the specifications; the moment of inertia of each disk calculated in Part 1.

Table 7 are the measurements for Part 2.

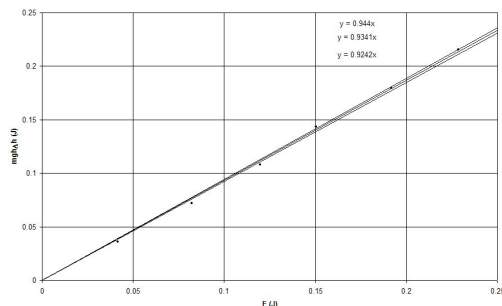


Figure 1:  $mgh\Delta h$  vs  $E$

Figure 1 demonstrates that energy is conserved.

## 2 Conclusion

### 2.1 Chris Payette

(Ed: I do'n't have Chris'.)

### 2.2 Neil Edelman

This experiment saw the investigation of a varied range of rotational collisions using air bearings to minimize friction. It was demonstrated that  $\Gamma = I\alpha$ , independent of the mass or rotation of the system, within a reasonable

error based on the number of trials.  $I$  was calculated experimentally using given values for the measurements of the disks and pulleys. The first measurement of velocity was not calculated where it did not fit with the other measurements because the initial time was not known except that it was at most 2 seconds; this is because the release was not coordinated with a measurement pulse. The error in System 3 was large, but reasonable for only 2 trials. In System 4, the same rotation was obtained as in System 1 leading to the conclusion that the air hose wasn't properly closed. Because of this, the analysis of the angular motion with the incorrect system configuration led to a meaningless value that did not (as it should not) agree with the conclusion. Next, the conservation of energy in rotational systems was confirmed by comparing  $mgh\Delta h : E$ , with a value of 0.93[1]. The discrepancy is easily accounted for especially by uncertainties in measurement of the position and time of the falling weight and also by friction. Finally, repeated measurements of angular momentum before and after multiple collisions between rotating discs of different masses were all consistently conservative within a reasonable error.

<b>System</b>	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>
<b>disk mass (kg)</b>	1.35900	1.35900	1.35900	1.35900
<b>disk radius (m)</b>	0.06328	0.06328	0.06328	0.06328
$I_{disk}$ (kgm <sup>2</sup> )	0.002720961533	0.002720961533	0.002720961533	0.002720961533
<b>disk 2 mass (kg)</b>				1.34517
<b>disk 2 radius (m)</b>				0.06316
$I_{disk2}$ (kgm <sup>2</sup> )				0.002683066397
<b>pully mass (kg)</b>	0.01000	0.01000	0.03600	0.01000
<b>pully radius (m)</b>	0.01250	0.01250	0.02500	0.01250
$I_{pully}$ (kgm <sup>2</sup> )	0.000000780625	0.000000780625	0.000011250000	0.000000780625
<b>hanging mass (kg)</b>	0.02443	0.04987	0.02443	0.02443
$I_{system}$ (kgm <sup>2</sup> )	0.002721742158	0.002721742158	0.002732211533	0.005404808555
<b>average <math>\alpha</math> (s<sup>-2</sup>)</b>	1.09272	2.187533333	2.67685	1.11156
$I\alpha$ (N)	0.002974102	0.005953902	0.00731372	0.006007769
$\Gamma$ (N)	0.002993441	0.006110638	0.005989277	0.002993441

Table 1: Part 1 Specifications

	<b>time, <math>t</math> (s)</b>	<b>digital reading</b>	$\omega$ (s <sup>-1</sup> )	$\alpha$ (s <sup>-2</sup> )
<b>System 1</b>	0	0	0.0000	
	2	20	0.6280	
	4	93	2.9202	1.1461
	6	163	5.1182	1.0990
	8	232	7.2848	1.0833
	10	298	9.3572	1.0362
	12	368	11.5552	1.0990
<b>System 2</b>	0	0	0.0000	
	2	83	2.6062	
	4	227	7.1278	2.2608
	6	365	11.4610	2.1666
	8	501	15.7314	2.1352
<b>System 3</b>	0	0	0.0000	
	2	72	2.2608	1.1304
	4	341	10.7074	4.2233
<b>System 4</b>	0	0	0.0000	
	2	13	0.4082	
	4	87	2.7318	1.1618
	6	156	4.8984	1.0833
	8	227	7.1278	1.1147
	10	296	9.2944	1.0833
	12	367	11.5238	1.1147

Table 2: Data for Part 1

drop, $h$ (m)	time (s)	$mg\Delta h$ (J)	$v$ ( $ms^{-1}$ )	$\omega$ ( $s^{-1}$ )	$\frac{1}{2}I\omega^2$ (J)	$\frac{1}{2}mv^2$ (J)	$E$ (J)	diff $E$ $mg\Delta h$
0.15	4.34	0.035935663	0.069124424	5.532166784	0.041649282	5.83655E-05	0.041707647	14.87
0.30	6.18	0.071871325	0.097087379	7.770098331	0.082161813	0.000115138	0.082276951	13.50
0.45	7.68	0.107806988	0.1171875	9.378751501	0.119703553	0.000167747	0.119871301	10.60
0.60	9.14	0.143742651	0.131291028	10.50748527	0.150250029	0.000210554	0.150460583	4.57
0.75	10.12	0.179678314	0.148221344	11.86245249	0.191498756	0.000268358	0.191767114	6.51
0.90	11.12	0.215613976	0.161870504	12.95482222	0.22839148	0.000320058	0.228711538	5.90

Table 3: Energy Conservation Data

$x = E$ (J)	$y = mg\Delta h$ (J)	$xy$ ( $J^2$ )	$x^2$ ( $J^2$ )	$(y - ax)^2$ ( $J^2$ )
0.041707647	0.035935663	0.001498792	0.001739528	0.000009146
0.082276951	0.071871325	0.005913354	0.006769497	0.000024851
0.119871301	0.107806988	0.012922964	0.014369129	0.000017364
0.150460583	0.143742651	0.021627603	0.022638387	0.000010205
0.191767114	0.179678314	0.034456392	0.036774626	0.000000297
0.228711538	0.215613976	0.049313404	0.052308968	0.000003882
Sums:		0.125732508	0.134600134	0.000065746

Table 4: Energy Conservation Calculations

$$a \left| \begin{array}{l} 0.934118745 \\ 0.009883868 \end{array} \right. \quad (a \text{ represents } mg\Delta h : E)$$

Table 5: Part 1b.

	mass, $m$ (kg)	radius, $r$ (m)
low steel disk (kg)	1.34517	0.06316
high steel disk (kg)	1.35900	0.06328
aluminium disk (kg)	0.47027	0.06313

Table 6: Part 2 Specifications

	top disk			bottom disk			collided system		
	digital reading	$\omega$ ( $s^{-1}$ )	ang.mom. ( $kg s^{-1}$ )	digital reading	$\omega$ ( $s^{-1}$ )	ang.mom. ( $kg s^{-1}$ )	digital reading	$\omega$ ( $s^{-1}$ )	ang.mom. ( $kg s^{-1}$ )
steel top	366	11.4924	15.6182				181	5.6834	15.3689
steel base	389	12.2146	16.5996				186	5.8404	15.7934
	350	10.9900	14.9354				177	5.5578	15.0292
	303	9.5142	12.9298				142	4.4588	12.0574
	321	10.0794	13.6979				161	5.0554	13.6707
aluminium top	378	11.8692	5.5817				95	2.9830	5.4155
steel base	354	11.1156	5.2273				92	2.8888	5.2444
	338	10.6132	4.9911				85	2.6690	4.8454
	307	9.6398	4.5333				77	2.4178	4.3894
	321	10.0794	4.7400				81	2.5434	4.6174
steel top	583	18.3062	24.8781	-728	-22.8592	-30.7495	-70	-2.1980	-5.9438
steel base	562	17.6468	23.9820	-494	-15.5116	-20.8657	22	0.6908	1.8680
	584	18.3376	24.9208	-475	-14.9150	-20.0632	31	0.9734	2.6322
	231	7.2534	9.8574	-45	-1.4130	-1.9007	89	2.7946	7.5571
	82	2.5748	3.4992	-494	-15.5116	-20.8657	-199	-6.2486	-16.8973
aluminium top	425	13.3450	6.2758	-294	-9.2316	-12.4181	-112	-3.5168	-6.3845
steel base	343	10.7702	5.0649	-246	-7.7244	-10.3906	-97	-3.0458	-5.5295
	249	7.8186	3.6769	-47	-1.4758	-1.9852	22	0.6908	1.2541
	386	12.1204	5.6999	-140	-4.3960	-5.9134	-8	-0.2512	-0.4560

Table 7: Part 2 Data

## A Sample Calculations and Error Analysis

### A.1 Part 1a

To calculate the angular velocity:

$$\begin{aligned}\omega &= \text{DigitalReading} \cdot 0.0314s^{-1} \\ &= 20 \cdot 0.0314s^{-1} \\ &= 0.628s^{-1}\end{aligned}$$

To calculate angular acceleration:

$$\begin{aligned}\alpha &= \frac{\Delta\omega}{\Delta t} \\ &= \frac{(2.9202s^{-1} - 0.628s^{-1})}{(4s - 2s)} \\ &= 1.1461s^{-2}\end{aligned}$$

To calculate moment of inertia of a disk or a pulley:

$$\begin{aligned}I &= \frac{M \cdot r^2}{2} \\ &= \frac{1.35900kg \cdot (0.06328m)^2}{2} \\ &= 0.002720962kgm^2\end{aligned}$$

To calculate the moment of inertia of a system:

$$\begin{aligned}I_{system} &= I_{disk} + I_{pulley} \\ &= 0.002720962kgm^2 + 0.000000780625kgm^2 \\ &= 0.002721742kgm^2\end{aligned}$$

To calculate average angular acceleration of a system:

$$\begin{aligned}\bar{\alpha} &= \frac{\sum_{i=1}^N \alpha_i}{N} \\ &= \frac{(1.1461s^{-2} + 1.099s^{-2} + 1.0833s^{-2} + 1.0362s^{-2} + 1.099s^{-2})}{5} \\ &= 1.09272s^{-2}\end{aligned}$$

To calculate the torque of system (method 1:)

$$\begin{aligned}\Gamma &= I_{system} \cdot \bar{\alpha} \\ &= 0.002721742kgm^2 \cdot 1.09272s^{-2} \\ &= 0.002974102N\end{aligned}$$

To calculate the torque of a system (method 2:)

$$\begin{aligned}\Gamma &= m \cdot g \cdot r \\ &= 0.02443kg \cdot 9.80643ms^{-2} \cdot 0.01250m \\ &= 0.002993441N\end{aligned}$$

## A.2 Part 1b

To calculate potential energy lost:

$$\begin{aligned}U &= m \cdot g \cdot h \\ &= 0.02443kg \cdot 9.80643ms^{-2} \cdot 0.15m \\ &= 0.035935663J\end{aligned}$$

To calculate the acceleration of the falling mass:

$$\begin{aligned}d &= V_o \cdot t + \frac{a \cdot t^2}{2} \\ a &= \frac{2 \cdot d}{t^2} \\ &= \frac{2 \cdot 0.15m}{(4.34s)^2} \\ &= 0.0159273ms^{-2}\end{aligned}$$

To calculate the velocity of the falling mass:

$$\begin{aligned}v &= \sqrt{2a \cdot \Delta h} \\ &= \sqrt{2 \cdot 0.0159273ms^{-2} \cdot 0.15m} \\ &= 0.069124424ms^{-1}\end{aligned}$$

To calculate the angular velocity of the disk:

$$\begin{aligned}\omega &= \frac{v}{r} \\ &= \frac{0.069124424ms^{-1}}{0.02499m} \\ &= 5.532166784s^{-1}\end{aligned}$$

To calculate rotational kinetic energy:

$$\begin{aligned}K_{rotational} &= \frac{I \cdot \omega^2}{2} \\ &= \frac{(0.002721742kgm^2)}{(5.532166784s^{-1})^2 \cdot 2} \\ &= 0.041649282J\end{aligned}$$

To calculate the kinetic energy due to the falling mass:

$$\begin{aligned}K_{falling} &= \frac{m \cdot v^2}{2} \\&= \frac{0.02443kg \cdot (0.069124424ms^{-1})^2}{2} \\&= 0.0000583655J\end{aligned}$$

To calculate the total kinetic energy:

$$\begin{aligned}E &= K_{rotational} + K_{falling} \\&= \frac{i \cdot \omega^2}{2} + \frac{m \cdot v^2}{2} \\&= 0.041649282J + 0.0000583655J \\&= 0.041708J\end{aligned}$$

To calculate percent difference between  $E$  and  $mg\Delta h$ :

$$\begin{aligned}P &= \frac{|E - mg\Delta h| \cdot 2}{E + mg\Delta h} \cdot 100\% \\&= \frac{|0.041708J - 0.035935663J| \cdot 2}{0.041708J + 0.035935663J} \cdot 100\% \\&= 14.87\%\end{aligned}$$

Finding the slope  $a$ :

$$\begin{aligned}a &= \frac{\sum xy}{\sum x^2} \\&= \frac{0.125732508J^2}{0.134600135J^2} \\&= 0.934118745\end{aligned}$$

Finding the error on  $a$ :

$$\begin{aligned}\sigma_a &= \sqrt{\frac{\frac{1}{N-1} \sum_{i=1}^N (y - ax)^2}{\sum x^2}} \\&= \sqrt{\frac{\frac{1}{5}(6.5746 \times 10^{-5}J^2)}{0.134600134J^2}} \\&= 0.009883868\end{aligned}$$

### A.3 Part 2

Calculating angular momentum:

$$\begin{aligned}L &= m \cdot \omega \\&= (1.34517kg + 1.35900kg) \cdot (-2.1980s^{-1}) \\&= -5.9438kgs^{-1}\end{aligned}$$